

#### PATENTED NON-CONTACT TECHNOLOGY

Joral true non-contact position sensors utilize patented technology developed in-house by Joral, LLC. Rare earth magnets take the place of physical shaft coupling for true non-contact installation. Proven in mobile hydraulics Joral non-contact position sensing enables fast installation, extreme tolerances, and exceptional durability.

- True non-contact technology for extreme installation tolerances
- Watertight, totally encapsulated electronics (IP69K)
- Rugged-duty, bullet-proof hardware
- Standard housings as well as application specific pages (standard housings 18mm, 30mm, 38mm, 58mm)
- LED indicators provide live feedback for power and output

#### NON-CONTACT GENERAL OPERATION

Measuring Micro

Internal Magnet (Built into Sensor)

External Magnet (Mounted on Application)

A magnetic coupling is made between an *internal rotating* magnet (built into the position sensor) and an external rotating magnet (mounted on the application).

The non-contact sensor's *internal rotating magnet* couples with the *external rotating magnet* installed on the application.

The external rotating magnet (mounted on the application) and the internal rotating magnet (built into the encoder) magnetically couple and track as if they were physically connected.

### AT-A-GLANCE SPECIFICATIONS

Installation Tolerances: GAP 0.5" (12mm) between application magnet

and encoder

**AXIAL** 0.10" (2.5mm) center alignment

**PLANAR** 30° tilt

**Connection options include but not limited to:** M12, M12 Pigtail, M8, Terminal Block, Flying Lead Cable, and various Deutsch connectors.

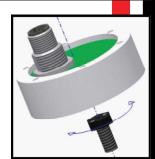
#### **Available Incremental Outputs:**

- Quadrature Single Ended
- Quadrature Differential
- Step and Direction
- J1939 CAN Bus

#### **Available Absolute Position Outputs:**

- SSI (Synchronous serial interface)
- Analog or Current Output
- PWM (Pulse width modulation)
- J1939 CAN Bus
- Modicon MODBUS

**ZERO POWER Multi-turn Capable** Contact Joral for available Zero Power options







#### Hockey Puck™& Prox Encoder™ Non-contact rotary position sensor HP58 / HP38 / PE30 / PE18

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# NON-CONTACT POSITION SENSORS

#### TRUE NON-CONTACT POSITION SENSING

Joral true non-contact position sensors compensate for variations in distance, tilt, and off-center positioning of the magnet.

- Tolerances of 0.5" (12mm) gap, 30° tilt, and 0.1" (2.5mm) axial
- True non-contact limits mechanical wear
- Magnetic coupling makes for flexible installation





### TOTALLY ENCAPSULATED ELECTRONICS

Automotive grade transparent potting compound protects electronic components and ensures a complete seal from external forces.

- Protection from shock, vibration, and direct impact
- IP69K protection for total moisture resistance
- Clear compound allows for LED indicators to be viewed

#### STANDARD PACKAGING STYLES

Joral non-contact senors available in prox-style and puck-style housings; 18mm & 30mm housings make for compact rotary position sensing.

- Small, standard, and convenient housing options
- Standard diameter and thread patterns
- Uses standard prox mounting hardware



PE18
ProxEncoder™
non-contact
rotary
position
sensor
displaying
compact
proximity
sensor
housing



#### LED INDICATORS FOR LIVE FEEDBACK

LED indicators allow for constant monitoring of the sensor's operation.

- Power LED displays the status of sensor's power connections
- Channel and index LEDs relay the status of encoder output
- LEDs make for simple in-field troubleshooting and diagnostics

#### RUGGED-DUTY HARDWARE

Additional protection from electrical surges and mis-wiring are built into Joral non-contact rotary position sensors.

- Surge protectors for every input/output
- Reverse voltage protection provided against mis-wiring
- Internal auto-resettable fuse for extreme protection

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## NON-CONTACT POSITION SENSORS

#### STANDARD OPERATING CHARACTERISTICS **ENCODER OUTPUT** RESOLUTION CHARACTERISTICS Quadrature Single Ended 8 to 2048 PPR - Standard Resolutions: Format: Two channel quadrature A and B outputs Incremental Output 8, 10, 16, 20, 32, 40, 50, 64, 80, 100, 125, 128, with index pulse Z 200, 250, 256, 400, 500, 512, 1024, 2048 Driver: 7272 push-pull driver **Quadrature Differential** 8 to 2048 PPR - Standard Resolutions: Format: Two channel quadrature A and B outputs with index Incremental Output 8, 10, 16, 20, 32, 40, 50, 64, 80, 100, 125, 128, pulse Z and complementary outputs A', B', and Z' 200, 250, 256, 400, 500, 512, 1024, 2048 Driver: 7272 push-pull driver Step and Direction 16 to 512 PPR - Standard Resolutions: Format: One channel STEP output and one channel DIRECTION Incremental Output 16, 32, 64, 128, 256, 512 output with Index pulse Z Driver: 7272 push-pull driver SSI Absolute Position Output Format: Clock and data output 8192 Positions Absolute Output 0.0439 degrees per position Driver: Differential Output **PWM Absolute Position Output** 1024 or 2048 Positions Format: Pulse Width Modulation in 1 µsec increments Absolute Output Driver: 7272 push-pull driver Analog Voltage Absolute Position 0 to 5 VDC -OR- 4 to 20 mA Format: Output Voltage/Current proportional to 0-360 degrees Absolute Output 10 bit internal resolution Output Loading: 10mA max .H939 CAN Bus 1000 or 8192 Positions - see J1939 output Format: Standard SAEJ1939 CAN Bus - One message for status, Absolute or Incremental Output pages for message information one message for settings

#### ELECTRICAL SPECIFICATIONS

Input Power 6 to 30 VDC at approximately 60mA max, not including output loads

Electrical Protection Over-voltage, Reserve-voltage, Output short-circuit protected

**LED Indicators** Power and output channel status

Connection Types M8, M12, M12 on pigtail, Terminal block, Flying lead cable, Deutsch - 4 or 6 pin

#### ENVIRONMENTAL SPECIFICATIONS

Operating Temperature -30 to +80 degrees C

Storage Temperature -40 to +100 degrees C

**Humidity** 100%

Vibration 5 to 3000 Hz, 20g

Shock 400g 6msec (MIL STD 202)

Sensor Sealing IP69K (connector dependent) \*\*Terminal block not IPrated\*\*

#### MECHANICAL SPECIFICATIONS

**Housing Diameter** 18mm, 30mm, 38mm, and 58mm

Housing Material Aluminum, Stainless Steel, or Delrin™

Max Speed 3000 RPM

Model	Housing Diameter	WEIGHT	Неіднт	HEIGHT W/ M12
PE18	18mm	1 oz	1.87 inches (47.5mm)	N/A
PE30	30mm	1.5 oz	1.2 inches (30.5mm)	1.75 inches (44.5mm)
HP38	38mm	1.3 oz	0.69 inches (17.5mm)	N/A
HP58	58mm	2 oz	0.75 inches (19.1mm)	1.5 inches (38.1mm)